rtified)

MAHARASHTF (Autonomous) (ISO/IEC - 2700



WINTER – 19 EXAMINATION

Subject Name: Tool Engineering

Model Answer

Subject Code:

22565

Page No: ____/ N

Important Instructions to examiners:

- 1) The answers should be examined by key words and not as word-to-word as given in themodel answer scheme.
- 2) The model answer and the answer written by candidate may vary but the examiner may tryto assess the understanding level of the candidate.
- 3) The language errors such as grammatical, spelling errors should not be given moreImportance (Not applicable for subject English and Communication Skills.
- 4) While assessing figures, examiner may give credit for principal components indicated in thefigure. The figures drawn by candidate and model answer may vary. The examiner may give credit for anyequivalent figure drawn.
- 5) Credits may be given step wise for numerical problems. In some cases, the assumed constantvalues may vary and there may be some difference in the candidate's answers and model answer.
- 6) In case of some questions credit may be given by judgement on part of examiner of relevant answer based on candidate's understanding.
- 7) For programming language papers, credit may be given to any other program based on equivalent concept.

Q.	Sub	Answer	Marking
No.	Q. N.		
1		Attempt any FIVE	5 x 2 =10
	a)	State the principle of Tool Engineering	
	Ans	Tool Engineering is a division of Production and Industrial Engineering. Its function is to plan the process of manufacture, develop various tools and machines and integrate facilities required for producing particular products with minimal expenditure of time, labour and material. Coursework is designed to include the art of designing jigs, fixtures, press tools, creating die casting designs, plastic moulds designs, mastering advanced plastic processing technologies and becoming perfect in metrology and measurements. It includes metal cutting, pressing, and various work holding devices. Metal cutting is the operation in which thin layer of metal is removed by wedge shaped tool. Metal cutting is commonly associated with industries like automotive, aerospace, home appliance etc. The machining of metal and allows play a crucial role in the range of	02
	b) Ans	appliance, etc. The machining of metal and alloys play a crucial role in the range of manufacturing activities including ultra precision machining of extremely delicate components to improve efficiency and productivity. Define the term Die clearance. Die clearance is the total space between cutting edge of die and punch. A correct clearance between the punch and the die assures normal wear of the tool and punching without defect such as: burrs on the piece in the case of excessive clearance and premature wearing of the tool and increased punching force in the case clearance being too small	02
		KALYAN DOMBIVLI THANE NERUL DADAR	/ NI

Contact - 9136008228

rtified)

MAHARASHTF (Autonomous) (ISO/IEC - 2700



	->- DIE CLEARANCE		
	Total Die Clearance = Die cle		
	both sides of Punch		
	Die Clearance 2		
	c) List the applications of CBN inserts		
A	ns 1.Abrasives products.	Any Four ¹ / ₂	
	2.Polycrystalline materials.	Mark Each	
	3.Metal processing for grinding.		
	4. Precision Machining. 5 CNC Machines Tools		
	1) State the functions of Locating Devices	Any Four 1/2	
A	ns 1] It should ensure workpieces are precisely positioned and rigidly supported.	Mark Each	
	2] It should be selected to ensure that the workpiece can be easily loaded and unloaded.		
	3] It should always contact a workpiece on machined surface.		
	4] It should be positioned as far apart as possible. This will ensure the use of fewer		
	locators and permits complete contact over the locating surface.		
	5] It should be fool proof.		
	e) Define the term Fixture	02	
A	ns A fixture is a work-holding or support device used in		
	the manufacturing industry. Fixtures are used to securely locate (position in a specific		
	location or orientation) and support the work, ensuring that all parts produced using the		
	fixture will maintain conformity and interchangeability. It does not guide the cutting		
	tool. Using a fixture improves the economy of production by allowing smooth operation		
	and quick transition from part to part, reducing the requirement for skilled labor by		
	simplifying how workpieces are mounted, and increasing conformity across a		
	production run.		
f)	List any four applications of Press tool	Any Four ¹ / ₂	
A	ns 1.Blanking 2.Piercing 3. Bending 4. Forming 5. Forging 6. Trimming 7.Parting	Marks Each	
	8.Drawing		
	g) Name the operations performed using Drawing operation	Any four $\frac{1}{2}$	
I	ns 1.Deep Drawing	Mark Each	
	2. Shallow Drawing		
	3. Bar drawing		
	4. Tube Drawing		
	5.Wire Drawing		

OUR CENTERS : KALYAN | DOMBIVLI | THANE | NERUL | DADAR Contact - 9136008228

MAHARASHTF (Autonomous) (ISO/IEC - 2700



2		Attempt any THREE	3 x 4 = 12	
	a)	Explain Merchant's Circle with neat sketch.		
	Ans	Merchant's Force Circle is a method for calculating the various forces involved in		
	the cutting process. The procedure to construct a merchants force circle diagram (using			
		drafting techniques/instruments) is,	O2 Marks	
		1. Set up x-y axis labeled with forces, and the origin in the centre of the page. The	Explanation	
		scale should be enough to include both the measured forces. The cutting force (F_c) is	02 Mortra	
		drawn horizontally, and the tangential force (F_t) is drawn vertically. (These forces will	02 Marks	
		all be in the lower left hand quadrant) (Note: square graph paper and equal x & y scales	Sketch	
	are essential)			
	2. Draw in the resultant (R) of F_c and F_t .			
	3. Locate the centre of R, and draw a circle that encloses vector R. If done correctly,			
	the heads and tails of all vectors will lie on this circle.			
	4. Draw in the cutting tool in the upper right hand quadrant, taking care to draw the			
		correct rake angle (a) from the vertical axis.		
		5. Extend the line that is the cutting face of the tool (at the same rake angle) through		
		the circle. This now gives the friction vector (F).		
		6. A line can now be drawn from the head of the friction vector, to the head of the		
		resultant vector (R). This gives the normal vector (N). Also add a friction angle (t)		
		between vectors R and N. As a side note recall that any vector can be broken down into		
		components. Therefore, mathematically, $R = F_c + F_t = F + N$.		
		7. We next use the chip thickness, compared to the cut depth to find the shear force.		
		To do this, the chip is drawn on before and after cut. Before drawing, select some		
		magnification factor (e.g., 200 times) to multiply both values by. Draw a feed thickness		
	tool cutting face (t_1) parametric the nonzontal axis. Next draw a chip thickness line parametric the			
		8 Drow a vector from the origin (tool point) towards the intersection of the two ship		
		3. Draw a vector from the origin (tool point) towards the intersection of the two employees stopping at the circle. The result will be a shear force vector (\mathbf{F}) . Also measure the		
		shear force angle between F_{s} and F_{s}		
		9 Finally add the shear force normal (F_r) from the head of F_c to the head of R		
		10 Use a scale and protractor to measure off all distances (forces) and angles		
		The resulting diagram is pictured below.		
		If students, write derivation than it is also acconted		
		ii students write derivation then it is also accepted.		

OUR CENTERS : KALYAN | DOMBIVLI | THANE | NERUL | DADAR Contact - 9136008228





·			ENGINEERING
	b) Ans	 the shear plane of the second of th	Any Eight ¹ / ₂ Each
		5. High thermal conductivity.	
		6. Lower coefficient of inction.	
		8 Resist Shock loads	
	c)	Differentiate between clamping and locating devices.	
	Ans	Locating devices:- 1] The workpieces position are accurately position with respect to tool guiding or setting	
		21 Locators should be positioned to contact the work on a machine surface.	
		3] Locators should be fool proof i.e the component can only be loaded into the fixture in	Any Four
		the correct position.	1 Mark Each
		4] Location features should be swarf traps and should have clearance provided where	
		necessary to clear machining burrs.	
		Clamping devices	
		1] The workpieces are held securely in located position during operations.	
		2] Clamping should be exerted on solid supporting of the work to prevent distortion.	
		OUR CENTERS :	

SOARD OF TECHNICAL EDUCATION rtified)



			ENGINEERING		
		4] Clamp should be positively guided to facilitate loading action			
	d)	Classify Jigs			
	Ans	Ans Type of jigs			
		1 Closed lig	Any Fight 1/2		
		1. Closed Jig	Mark Each		
		2. Plate Jig	Mark Laon		
		3. Sandwich Jig			
		4. Angle plate jig			
		5. Box Jig			
		6. Channel Jig			
		7. Trunnion Jig			
		8. Pump Jig			
		9. Indexing Jig			
		10.Template jig			
		11.Multi section Jig			
		12.special jig			
		13.Leaf Jig			
		14. Latch Jig			
3		Attempt any THREE	3 x 4 =12		
	<u>a)</u>	a) Explain with neat skatch importance of 'Scrap strip layout'			
	<i>a)</i>	In the blanking die-set design, the first step is to prepare blanking layout i.e. the position			
		of the work pieces in the strip and their orientation with respect to each other. This is	4 Marks		
		known as Scrap Strip Layout. Importance of scrap strip layout due to following factors			
		1. Economy of Material: As per arrangement in below fig.below it can be worked at			
		single row, single pass with a single punch.	(Sketch is		
			for 1 mark)		
			and		
			(3 Marks for		
		2. By feeding the material as per below fig. there is increase in maximum material utilization up to some extent	Explanation)		
			. ,		
		2 Polow figure chows a single row double pass strip. Uses strip will have to be passed through			
		5. Delow light shows a single row, double pass strip. Here, strip will have to be passed through the dies second time. Hence, there is a maximum			
		utilization of the material and reduction in scrap			



rtified)



	ha - dto Bander - Partic PC	
	4. Scrap strip layout gives an idea on the positioning of various punches, stops and pilots	
 b)	State the Causes of spring back:	4 Marks
Ans	i Spring back increases as hardness of stock material increases	(anv four
	i. Thickness of stock material	points)
	1. The kness of stock indefinit.	
	111. Spring back is directly proportional to the bend radius.	
	IV. Due to the displacement of molecules and the other considers spring back in terms	
	$v_{\rm A}$ is one of the reasons for Spring Back is that as the material is bent the inner region	
	of the bend is compressed while the outer region is stretched. This means that the	
	molecular density is greater on the inside of the bend	
	vi. The compressive strength of material is greater than it tensile strength. This means that	
	pressure will permanently deform the outer regions of the piece before it deforms the inner	
	regions. The compressive stress is changed into Spring Back	
c)	Classify the Dies. List their application	
Ans	Disc are Classified based on sutting and all this parties	4 Marks
	Dies are Classified based on cutting and shearing action	i marko
	• Blanking dies	
	• Piercing dies	
	Perforating dies	(2 Marks for
	• Lancing	classification)
	Notching	Any
	Trimming	classification
	• Shaving	should give
	• Nibbling dies	marks
	Dies are Classified based on method of operation	
	Simple dies	
	• compound dies	
	 combination dies 	
	prograssive dias	And
	• progressive dies	
	• transfer dies	
	• multiple dies	(2 marks for
	Application.	, any two
	2 Boiler manufacturing	Application)
	3 Pressure vessel tank manufacturing	,
	4. Chassis door cabinets in Automobile Industry	
	5. Chemical processing equipment and Jewelry	
	6. Food & beverage – grain drvers, sorting machines, fruit and vegetable juice	
	presses, cheese molds, baking travs, coffee screens.	
	7. Tube notching is in the manufacture NTERS to frames	
	KALYAN DOMBIVLI THANE NERUL DADAR Page No.	/ N
	Contact - 9136008228	/ ``



OUR CENTERS : KALYAN | DOMBIVLI | THANE | NERUL | DADAR Contact - 9136008228



OUR CENTERS :

KALYAN | DOMBIVLI | THANE | NERUL | DADAR Contact - 9136008228

(Autonomous) (ISO/IEC - 2700

rtified)

MAHARASHTF



HSS: 2 Marks1. Used for making drill and reamers, milling cutters, turning tools, taps, dies, broach, hobs, etc.2. Solid tool of HSS3. HSS Inserts: shanks are friction welded to HSS cutting ends.4. HSS strips are Electron beam welded to low alloy steel for making band saws.5. Indexable HSS insets for CNCc)c)Explain the term degree of freedom. State its importance while selecting, locating and clamping devices. Ans:Degrees of Freedom : v_{1} v_{2} v_{3} v_{4} v_{1} v_{1} v_{1} v_{1} v_{2} v_{1} v_{1} v_{2} v_{1} v_{2} v_{3} v_{4} <td< th=""><th>arks rk for e of</th></td<>	arks rk for e of
 1. Used for making drill and reamers, milling cutters, turning tools, taps, dies, broach, hobs, etc. 2. Solid tool of HSS 3. HSS Inserts: shanks are friction welded to HSS cutting ends. 4. HSS strips are Electron beam welded to low alloy steel for making band saws. 5. Indexable HSS insets for CNC c) Explain the term degree of freedom. State its importance while selecting, locating and clamping devices. Ans Degrees of Freedom : (1 Marcial for the form degree of freedom in an intrinsic number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along x-axis, y-axis and z-axis. It can move along my of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate the translational and 	arks rk for e of
 etc. 2. Solid tool of HSS 3. HSS Inserts: shanks are friction welded to HSS cutting ends. 4. HSS strips are Electron beam welded to low alloy steel for making band saws. 5. Indexable HSS insets for CNC c) Explain the term degree of freedom. State its importance while selecting, locating and clamping devices. Ans: Degrees of Freedom : <i>i</i> <i>i</i> <i>i</i> <i>i</i> <i>i</i> <i>i</i> i i i i i <i>i</i> <i>i</i> <i>i</i> i i <i>i</i> <i>i</i>	arks rk for e of
 a. HSS linests: shanks are friction welded to HSS cutting ends. b. HSS strips are Electron beam welded to low alloy steel for making band saws. c) Explain the term degree of freedom. State its importance while selecting, locating and clamping devices. Ans: Degrees of Freedom : a. HSS b. Degrees of Freedom : b. Tree beam of the term degree of freedom. State its importance while selecting, locating and clamping devices. Ans: Degrees of Freedom :	arks rk for e of
 A HSS strips are Electron beam welded to low alloy steel for making band saws. Indexable HSS insets for CNC C) Explain the term degree of freedom. State its importance while selecting, locating and clamping devices. Ans: Degrees of Freedom : Importance while selecting, locating and clamping devices. Ans: Degrees of Freedom : Importance while selecting, locating and clamping devices.	arks rk for e of
s. Indexable HSS insets for CNC 6 M c) Explain the term degree of freedom. State its importance while selecting, locating and clamping devices. Ans: 6 M Degrees of Freedom : (1 Ma figure degree of freedom is the term degree of freedom. Any rectangular body has selected three axes along x-axis, y-axis and z-axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beded arrows indicate the translational and term of the term degree is the term degree in the translational and term of the term degree in the translational and term of the term degree in the	arks rk for e of
c) Explain the term degree of freedom. State its importance while selecting, locating and clamping devices. Ans: 6 W Degrees of Freedom : (1 Min figure degrees) use of the provide of the provide degrees of the provide degre	arks rk for e of
Ans and clamping devices. Ans: Degrees of Freedom : Image: the second	rk for e of
Ans: Degrees of Freedom : $I = \frac{1}{2} \int_{1}^{2} \int_{1$	rk for e of
Degrees of Freedom :(1 Ma figu degr freeImage: space of freedom is provided and z-axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate, the translational and(1 Ma figu degr freeImage: space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along x-axis, y-axis and z-axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate, the translational and(2 Ma loci impo any point	rk for e of
Degrees of Freedom : $I = \frac{1}{2} \int_{0}^{1} $	e of
I_{ij} degines in the second secon	
Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate the translational and	-e of
$ \begin{array}{c} 1 \text{ Matrix} \\ 1 \text{ Matrix} $	lom)
(1 Ma expla for se and	,
 (1 Ma expla for se and Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i>-axis, <i>y</i>-axis and <i>z</i>-axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate, the translational and 	
 Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i>-axis, <i>y</i>-axis and <i>z</i>-axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-headed arrows indicate, the translational and 	rk for
Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-headed arrows indicate, the translational and	n IUI
Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-headed arrows indicate, the translational and	octing
Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-headed arrows indicate, the translational and	
Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate, the translational and	,01)
Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate, the translational and	
Fig. Degree of Freedom A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate, the translational and	
A workpiece free in space can move in an infinite number of directions. For analysis, this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate, the translational and	ks for
this motion can be broken down into twelve directional movements, also called as degrees of freedom. Any rectangular body has selected three axes along <i>x</i> -axis, <i>y</i> -axis and <i>z</i> -axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-beaded arrows indicate, the translational and	ting
degrees of freedom. Any rectangular body has selected three axes along x-axis, y-axis and z-axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-headed arrows indicate, the translational and	tance
and z-axis. It can move along any of these axes or any of its movement can be released to these three axes. As the double-headed arrows indicate, the translational and	lw0 htc)
to these three axes. As the double-headed arrows indicate, the translational and	1137
to mote mice anos its way addete neaded allows indicate, the translational and	
rotational positions six axial & six radial can vary in either direction with respect to	
each of the three axes. These twelve coordinates are known as the twelve degrees of	ks for
freedom of a three-dimensional object.	ping
Impo	tance
Importance of Locating:	lw0
por	115)
1] A desired relationship between the workpiece and the jigs or fixture correctness of	
location directly influences the accuracy of the finished product.	
[2] Any locator is to reference the workpiece and to ensure	
repeatability/Interchangeability.	
3] Restrict the undesired movement and rotation of workpiece.	
4] Determine the position of the workpiece with respect to cutting tool.	
Importance of clamping device:	
(a) It should rigidly hold the workpiece.	
(b) The workpiece being clamped should not be damaged due to application of clamping	
pressure by the clamping unit.	
(c) The clamping pressure is enough to overcome the Operating pressure/Cutting	
Force applied on the workpiece as both pressure acts on the workpiece in opposite	

KALYAN | DOMBIVLI | THANE | NERUL | DADAR Contact - 9136008228





		directions	I		
		(d) Clamping device is capable to be unaffected by the vibrations generated during an			
		operation.			
		(e) It should also be user friendly, like its clamping and releasing should be easy and			
		less time consuming. Its maintenance will also be easy.			
		f) Clamping pressure is directed towards the support surfaces or support points to			
		prevent undesired lifting of workpiece from its supports.			
		(g) Clamping faces is hardened by proper treatments to minimize their wearing out.			
		(n) To nancie the workpieces made of fragile material the faces of clamping unit is equipped with fiber pads to avoid any damage to workpiece.			
5		Attempt any Two	2 x 6 = 12 M		
	a)	Explain the procedure of designing fixture for milling machine in detail			
	Ans	Designing of milling fixture involves following design stages			
		[1] The milling component analysis with respect to the dimensions, degree of freedom is			
		carried out			
		[2] Operator safety, processing equipment, ease of use is considered on milling machine			
		[3] All the critical dimensions and feasible datum areas of milling component are	(Manlar		
		examined	o Marks		
		[4] Degree of freedom need to be arrested are decided			
		[5] In further steps the clamping scheme is designed in such a manner that it will be easy			
		to clamp and unclamp component without damaging it.			
		[6] In Next step the locating pins are designed in such a manner that it will not interfere			
		with tools or milling cutters			
		[7] Tool guiding schemes are designed which are to be consistent with clamping and			
		tool guiding arrangements			
		[8] Finally there is the design of the structure of the fixture body frame. This is generally			
		built up around the workpiece and usually single element which links all the other			
		elements used for locating, clamping, tool guiding into integral frame work			
	b)	The washers of 25 mm outer diameter & 10 mm inner diameter are to be made by			
		press operation from M S Sheet of 1 mm thickness Calculate			
		(i)Clearance(ii)Size of punch and die			
	Ans	(i) Clearance : 5 % of the thickness t			
		$C = 0.05 \times 1$			
		OUR CENTERS :	2 Mark [A]		
	I	KALYAN DOMBIVLI THANE NERUL DADAR Page No:	/ N		

MAHARASHTF (Autonomous) (ISO/IEC - 2700



	= 0.05 mm[A]	
	(ii) Size of punch and die.	
	Blanking die opening size is equal to blank size. But to allow for expansion of blank,	
	die opening should be made smaller, thus	
	Blank die opening = $25 - 0.05$	1 Mark [B]
	= 24.95 mm[B]	
	Blanking punch size = Blanking die opening - $2C$	
	$= 24.95 - 2 \times 0.05$	1 Mark [C]
	= 24.85 mm[C]	
	Punch size is made larger to compensate elastic recovery	
	Piercing Punch size $= 10 + 0.05$	1 Mark [D]
	= 10.05[D]	
	Piercing die size = Piercing Punch size + $2C$	
	$= 10.05 + 2 \times (0.05)$	1 Mark [E]
	= 10.15 mm[E]	OR
	OR	ÖN
	(iii) Size of punch and die.	1 Mark [B]
	Blank die opening = Blank size = 25.00 mm [B]	
	Blanking punch size = Blanking die opening $-2C$	
	$= 25.00 - 2 \times 0.05$	1 Mark [C]
	= 24.90 mm[C]	
	Punch size is made larger to compensate elastic recovery	1 Mark [D]
	Piercing Punch size = Hole size (dia) = 10 mm[D]	
	Piercing die size = Piercing Punch size $+ 2C$	
	$= 10.00 + 2 \times (0.05)$	1 Mark [E]
	= 10.10 mm[E]	
	Note :- The given problem can solve by any one of the above way, Consider any one	
	solution out of the above two	
c)	Determine the developed length of part shown in Figure. Assume $K = t/3$	

MAHAR (Autonom (ISO/IEC	ASHTF ous) C - 2700	SOARD OF TECHNICAL EDUCATION rtified)	SEE & DIPLOMA
		$R = 3.2 \text{ mm}$ $R = 3.2 \text{ mm}$ $R_1 = 0.09 \text{ mm}$ $R_2 = 90^{\circ}$ $R_1 = 0.09 \text{ mm}$ $R_2 = 90^{\circ}$	ENGINEERING
	Ans	 While calculating the developed length for bending, external dimensions should be converted to internal dimensions. Developed length = L1 + L2 + BFormula 	1 Mark for Formula
		The inside radius of bend, $r = 3.2 - 2.3 = 0.90 \text{ mm}$ [A]	1 Mark [A]
		Length $L1 = 76 - (2.3 + 0.90) = 72.8mm$ [B]	1 Mark [B]
		Length L2 = $115 - (2.3 + 0.90) = 111.8 \text{ mm}$ [C] Bend allowance B = $\alpha / 360 2 \pi (r + K)$	1 Mark [C]
		$a = 90^{\circ} K = 0.5$ B = 90/360 2 \pi (0.90 + 2.3/3)	
		= 2.61 mm [D]	1 Mark [D]
		Developed Length = 72.8 + 111.8 + 2.61 = 187.21 mm[E]	1 Mark [E]
6		Attempt any Two	2 X 6 = 12 M
	a)	Explain with neat sketch the construction of jig for drilling four equispaced through radial holes in a ring	
	Ans	This type of jig is equipped with the facility of indexing, which creates positional	
		division of the work piece suitably. This jig is used for quick drilling of equidistant	4 Marks for
		holes on the circular surface of the work piece. By means of indexing device a hole is drilled then the work piece is moved (indexed) to pext position under the drill bush for	««««»»»»»»»»»»»»»»»»»»»»»»»»»»»»»»»»»»
		drilling automatically. Indexing jigs are used to accurately space holes or other	a 2 Marks for
		machined areas around a part. To do this, the jig uses either the part itself or a reference	neat sketch
		plate and a plunger. Larger indexing jigs are called rotary jigs.	





Contact - 9136008228

MAHARASHTF (Autonomous) (ISO/IEC - 2700



Ratio lies between 07 to 1.5 & henc		
	e number of draws are 2[E]	1 Mark [E]
C) Explain the following terms (i) Centre of pressure (ii) Die block (iii) Die shoe		
Ans (i) Centre of pressure		
When the shape of blank to be cut is	irregular, the summation of shear forces about the	
centre line of press ram may not be s	symmetrical. Due to this, bending moments will be	
introduced in the press ram, produc	ing misalignment and undesirable deflections. To	
avoid this "centre of pressure" of the	shearing action of the die must be found and while	
laying out the punch position on the	punch holder, it should be ensured that the centre	
line of press ram passes exactly throu	gh the centre of pressure of the blank. This "centre	2 Marks each for
of pressure" is the centroid of the line	e perimeter of the blank. It should be noted that it is	correct
not the centroid of the area of the blan	ık.	explanation
(ii) Die Block		
It is a block or a plate which contain	as a die cavity. Die block is the female half of the	
two mated tools which carry the cutt	ing edges. It is subjected to extreme pressures and	
wear conditions. Hence a die block is	made of a superior quality of tool steel.	
(iii) Die Shoe		
Die shoes are generally two types 1]	upper shoe 2] Lower shoe. Upper shoe is a part of	
die set and usually contains guide p	ost bushings. Lower shoe is generally mounted on	
the bolster plate of a press. The die b	lock is mounted on the lower shoe. Also the guide	
posts are mounted in it.		

OUR CENTERS : KALYAN | DOMBIVLI | THANE | NERUL | DADAR Contact - 9136008228